# Deep Beam Design Using Strut-Tie Model

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## ABSTRACT

The aim of this paper is to develop nomographs and demonstration of its applicability for the simple supported deep beam design in order to simplify a number of computation steps. For this purpose, the applied basic modifications of formulation of the Strut-Tie model for the deep beam design ware briefly described. For the demonstration of the applicability of the developed nomographs, a simple supported deep beam subjected to uniformly distributed load was analyzed in which the flexural design was focused. The influence of the column was considered, simplifying by the concerning of the width, but not length of the column.

KEYWORDS: Strut-Tie model, Deep beam design, Height-span ratio

## **1. INTRODUCTION**

Reinforced concrete deep beams are typically used as transfer members in high-rise structures due to their high resistance capacity. Also they often have a function to convert the structural system between upper and lower part of the structure. Since a deep beam has to support the whole of upper part structure, its structural behavior can influences on the stability and safety of the structure remarkably. Because the stress distribution in the section of the deep beam is nonlinear, the linear elastic theory for the general beam analysis can not be applied. Therefore ACI code requires that deep beams be designed via non-linear analysis or by Strut-Tie models.

The Strut-Tie model is formulated by straight lines expressing resultant forces of tension and compression stress in members and its section. Therefore, the merit of the concept can be that the design engineer grasps the flow of the force in the members and proposes the rational reinforcing recipe for the stress disturbance region due to the process of the representation of the natural flows of forces. With these advantages of the Strut-Tie model, the application of this method seems like quite easy and practical. However, if one will use the model for the design practice, he will immediately notice several difficulties. First of all, the user has to carry out a number of calculation steps according to the design scheme under some initial assumptions which should be checked only after several strenuous, suggested in ACI, computation process. In addition to, the result of design the using Strut-Tie model indicates in some cases remarkable discrepancy with them using other building codes, like ACI code (2005) or CEB-FIP (1990).

The aim of this paper is to develop nomographs and demonstration of its applicability for the simple supported deep beam design in order to simplify a number of computation steps. Prior to this, the applied basic modifications, discussed in detail in Noh et al.(2006), in the formulation of the Strut-Tie model for the deep beam design briefly described. For this purpose, a simple supported deep beam subjected to the uniformly distributed load was analyzed in which the flexural design was focused in the paper. The influence of the column was considered, simplifyed by the concerning of

the width, but not length of the column. As the main investigation parameter, the height-span ratio of the beam was chosen.

## 2. MODIFICATIONS OF STRUT-TIE MODEL FORMULATION

#### 2.1 Maximum moment

The basic concept and calculation scheme of the Strut-Tie model can be found in many literatures, such as Schaefer (1996), Rogowsky and Macgregor (1986), Marti (1985) as well as Kong (1970).





Figure 2. Span modification factor  $\alpha$ 

Figure 1 shows the principal stress paths in the simple supported deep beam subjected to the uniformly distributed load and the generally applied strut-tie model with two equivalent concentrated loads substituted from the original load. This Substitution is allowed, only if the equality of the maximum moments, the most fundamental value in the Strut-Tie model application, at the mid-span of the both systems is guaranteed. In the fact, the above concept does not correctly consider the columnwidth (column stiffness) and the height-span ratio which influence the flows of the compression stress and further the tension stress. The author suggested in Noh et al. (2006) the modification of the substituted concentrated load  $p_{mod}$  for the computation of the maximum bending moment in the deep beam, considering the height-span ratio and column width as follow:

$$p_{\rm mod} = w_{\rm mod} l/2 \,, \tag{1}$$

$$w_{\text{mod}} = w(l_{\text{mod}} / l_0)^2 \text{ with } l_{\text{mod}} = l_n + a \times \alpha$$
(2)

Where

W	: uniformly distributed load,	$W_{mod}$	: modified uniformly distributed load,
$p_{\rm mod}$	: modified converted concentrated load,	$l_{\rm mod}$	: modified span according to Figure 2,
$l_0$	: column-centroid span,	α	: column width.

The span modification factor  $\alpha$  can be computed by the Eq.(3), (4) and (5)

$$\alpha = 7.4 \times h/l - 2.2 \text{ for } 0.2 < h/l \le 0.35$$
 (3)

$$\alpha = 1.3 \times h/l - 0.1 \quad \text{for} \quad 0.35 < h/l \le 0.6 \tag{4}$$

$$\alpha = 0.5 \text{ for } h/l > 0.6$$
 (5)

#### 2.2 Limit of angle between inclined strut and tie

ACI code defines the lower limit of the angle  $\theta$  between the inclined strut and the tie as 25° based on the principal of Saint-Venant. This lower limit guarantees that B-region does not exist in the beam and trapezoidal Strut-Tie model may be applied. On the other hand, the upper limit of the angle is not

stated in the code. Schlaich et al. (1987, 1991), however, suggested the limit as about  $68^{\circ}$ . In our investigation using FE-analysis, with the consideration of the column width of 1.0 *l*, the tensile force does not change, when h/l greater than about 1.2. The angle  $\theta$  converges consequently to about  $72^{\circ}$ . The result indicates that in the case of the beam with h/l greater than about 1.2, the upper part of the beam should be modeled as B-region.

#### 2.3 Limit of tie width

The horizontal strut width  $W_s$  and the tie width  $W_t$  can be computed by the equation formulated by the equality requirement of the compression and the tensile forces. Under this condition, the relationship between the widths of the strut and the tie can be found as

$$W_t = 1.25W_s \tag{6}$$

which results from the ratio of the strength reduction factor for the strut with uniform cross-section  $\beta_s = 1.0$  and for the nodal zone anchoring in the tie  $\beta_s = 0.8$  according to ACI. However, the amount of  $W_t$  can be possibly evaluated smaller than the required width for the arrangement of reinforcement bar. Therefore the lower limit of  $W_t$  should be taken as the diameter of the bars plus twice the covering depth according to ACI code. For the practical application, the lower limit of the tie width  $W_t$  was suggested in this paper as 10cm.

$$_{Min}W_t = 2c + ds \ge 10cm \tag{7}$$

#### **3. STRUT-TIE MODEL ANALYSIS**

In the following, the design process for the deep beam using the Strut-Tie model according to ACI code was briefly described.

Step 1 : Substitute uniformly distributed load to two concentrated loads

Step 2 : Calculate reactions and maximum moment at mid-span Step 3 : Assume widths of horizontal strut( $S_{horz}$ ) and tie (*Tie*) at mid-span

Step 4 : Calculate distance jd between centroid of  $S_{horz}$  and *Tie* 

Step 5 : Calculate angle  $\theta$  between inclined strut( $S_{horz}$ ) and *Tie* 

Step 6 : Calculate forces in strut,  $C_{horz}$  and in tie  $C_{inc}$ 

Step 7 : Check strength in strut and tie

Step 8 : Check strength of nodes A

Step 9 : Check assumed widths of strut and tie at step 3 by control of node geometry

Step 10 : Calculate flexural reinforcement steel  $A_s$ 

Step 11 : Calculate shear reinforcement steel  $A_{VS}$ 



Figure 3. Degree of freedom of deep beam

The most uncertain and annoying step in the analysis process can be to assume the widths of the strut and the tie at step 3 and the recalculation with the new widths, if this assumption does not pass the check at step 9. This stress can be mitigated through the solution of second degree polynomial

equation formulated by the requirement of the equality of the horizontal compression and the tension forces as well as the equilibrium condition of the moment at mid-span.

## 4. DEEP BEAM DESIGN USING NOMOGRAPHS

In consideration of the modification components mentioned above, nomographs of the deep beam design using Strut-Tie model were built up.

Table 1. Design data

Beam depth	Clear spans	Column	Load	Concrete strength
(h)	$(l_n)$	$(a \times b)$	(W)	$(f_{ck})$
( <i>m</i> )	( <i>m</i> )	$(m \times m)$	(kN/m)	$(MN/m^2)$
3.0	3.0	0.4×0.5	2000	40.0

#### **Process 1: Substituted concentrated load** $P_{mod}$

The substituted concentrated load  $P_{\text{mod}}$  can be computed by Eq. from (1) to (5). With the height-span ratio h/l = 0.79 and the span modification factor  $\alpha = 0.5$ ,  $P_{\text{mod}}$  results in 3011.7kN. This step corresponds Step 1 in Sect.3.

#### Process 2: Width of strut and tie

By the requirement of the equality of the horizontal compression and the tension forces as well as equilibrium condition of moment at mid-span, a second degree polynomial equation for strut width  $W_s$  can be formulated.

$$pW_{s}^{2} - qW_{s} + P_{\text{mod}} l_{0} / (4 \cdot f_{ck} \cdot b) = 0$$
(8)

$$p = 1.125\phi \cdot 0.85\beta \tag{9}$$

$$q = \phi \cdot 0.85 \cdot \beta_s \cdot h \text{ with } \phi = 0.75 \tag{10}$$

The solution of Eq.(8) was plotted in dependence upon h,  $P_{mod}l_0/(f_{ck} \cdot b)$  in Figure 5 from which the required width of the horizontal strut  $W_s$  can be easily read out. Then, the width of the tie can be found by Eq.(6). This process includes the uncertain and annoying step 3 and control step 7 and 9 mentioned in Sect. 3.

For the given beam,  $W_s$  indicated 7.0*cm* for h = 3.0cm and  $P_{mod}l_0/(f_{ck} \cdot b) = 0.51cm^2$ .  $W_t$  was calculated by Eq.(6) as 8.75*cm*. However, in consideration of the lower limit of the tie width by Eq.(7),  $W_t$  was chosen as 10cm.

#### Process 2: Width of strut and tie

Strength of each node is determined by the size of the strut and the tie as well as the widths of the acting load or the support width depending on the location of the node. In the case of the distributed load, the node constructed under the substituted concentrated load has not to be controlled, because the node does not exist actually. So, only the node above the support should be controlled.

With the assumption that the width of the support  $l_b$  is sufficiently designed against the support reaction, the inclined width  $W_s$  of the support node in Figure 4 should be ensured do that the reduced norminal strength  $\phi F_{ns}$  is greater than the acting force  $C_{inc}$  in the inclined strut.

$$\phi F_{ns} = \phi \left( 0.85 \beta_s f_{ck} \right) b \cdot W_{SA} \ge C_{inc} = P_{\text{mod}} / \sin \theta$$
(11)

$$W_s = l_b \sin \theta + W_t \cos \theta \tag{12}$$

From Eq.(11,12) the minimum width of the tie  $W_t$  can be obtained as

$$_{\min}W_{t} = \frac{P/f_{ck} \cdot b}{\phi \cdot 0.85 \cdot \beta_{s} \cdot \sin \theta \cdot \cos \theta} - a \tan \theta$$
(13)

This Equation for  $_{\min}W_t$  is plotted in Figure 6 in which the angle  $\theta$  has to be pre-calculated as follows.

$$\theta = \tan^{-1} \left( \frac{jd}{l_0 / 4} \right) \text{ with } 25^\circ \le \theta \le 72^\circ$$
(14)

$$jd = h - \frac{W_t}{2} - \frac{W_s}{2} \tag{15}$$

In the applied example,  $_{\min}W_t$  was found out as 0cm, so that the width from the support  $l_b \sin \theta$  is sufficiently large. Therefore,  $W_t$  of 10cm obtained in Process 2 is valid.



**Process 4: Amount of required flexural reinforcement** The total amount of required flexural reinforcement for the tension force in the tie can be computed from Eq.(16), which pictured in Figure 7.

$$A_s = T/\phi f_y = P_{\text{mod}} \tan \theta / \phi f_y \tag{16}$$

The authors suggest that the strength reduction factor  $\phi$  in Eq.(16) might be 0.9, since the problem concerns the flexural reinforcement, although ACI consider the deep beam design as shear design and recommends  $\phi$  as 0.75.

For the given example, the required reinforcement amount can be read out from figure 7  $A_s = 27cm^2$  for  $P_{mod} = 3011.7kN$  as well as  $\theta = 72^\circ$ .

The process for the evaluation of the shear reinforcement, which is not described in the paper can also formulated in the same way.



Figure 5. Width of strut

ACI(2005)

Figure 6. Minimum width of the tie



Figure 7. Amount of required flexural reinforcement

### 5. CONCLUSIONS

The paper demonstrated the development process of nomographs and its applicability for the simple supported deep beam design in order to simplify a number of computation steps.

Prior to this, the applied basic modifications of formulation of Strut-Tie model for the deep beam briefly described. For this purpose, a simple supported deep beam subjected to the uniformly distributed load was analyzed. With this concept, an engineer can easily design a deep beam with only 3 nomographs and some simple calculation processes, without the uncertain and annoying steps.

With the same concept, the design processes with nomographs for a concentrated load and further for a multiple scan beam can be developed.

# AKNOLOFYMENT

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